

345 - LECTURE 4 - PARTIAL FRACTION EXPANSION - PART 2

BIG Picture Review:

- dynamic systems are modeled using diff. eqns.
- diff. eqns. are hard and messy and time consuming
- Laplace turns diff. eqns. into algebra
 - when I first learned this as a senior at MIT, I was baffled that we didn't learn this sooner
- we are going to use the table for both forward and inverse Laplace
 - I have done a few derivations
 - I will not ask you to do any
 - I want you to know where the table comes from and that it isn't magical

ONE MORE NOTE ON *
WHY MY TABLE IS SO SHORT

- partial fraction expansion is the key to using the table for inverse Laplace

FOOT NOTES

* Dynamic systems and control is what I do.
Laplace is how I think about systems.

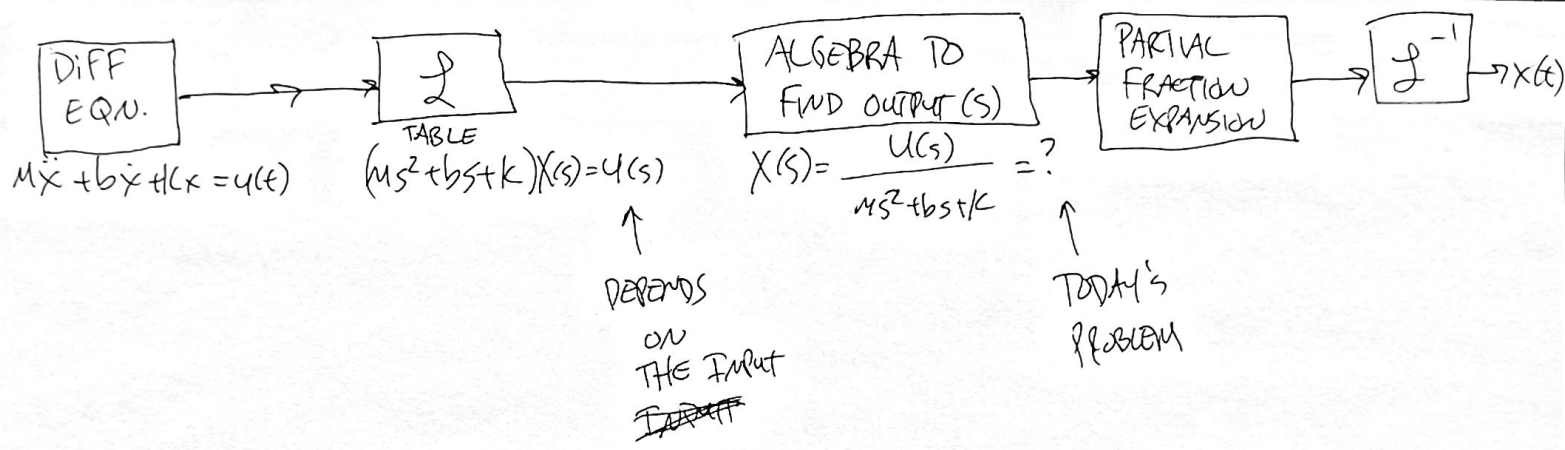
But I don't carry a table in my pocket.

I don't know any controls experts
who carry around Laplace tables.

→ the one page table contains the
essentials

- you can probably solve 95% of
d.s. & control problems with it

→ it contains what I have unintentionally
committed to memory over the years



EGR 345 - LECT 4 - PARTIAL FRACTION EXPANSION - PART 2

- Partial Fraction Expansion is all that stands between us and being fully able to solve diff. eqns. via Laplace

- We said there are 3 steps to partial fraction expansion and 3 cases we need to learn how to handle

- we have already learned 2 cases

- 3 steps:

1. recognize roots/poles

2. solve for unknown coeff. (mostly in numerators)
↑ of the denominator

3. look up individual terms in the table

- 3 cases:

1. distinct real roots

2. repeated roots

3. complex conjugate pairs of roots